

Call for Papers

Special Issue – Robotics Law and Policy

Introduction

Human-robot interaction (HRI) is a thoroughly interdisciplinary field, bridging computer science, design, psychology, and many other areas of study. Studies of law and policy, however, seldom inform or draw from HRI research. Yet understanding how people and robots interact is critical to developing sensible policy across a variety of public and private sectors.

With this special issue, the Journal of Human-Robot Interaction aims to jumpstart the conversation between HRI and the field of law and policy. We invite rigorous, original research concerning the ways in which HRI theory, methods, and experimental results may bear on evolving questions of autonomy, responsibility, harm, and other core issues of law and policy. Collaborations across disciplines are especially encouraged.

Indicative Topics

Topics of interest include, but are not limited to: consumer law; criminal law; damages; drones; driverless cars; elder care; healthcare; intellectual property; laws of war; maritime law; personal robotics; privacy, tort law; theories of punishment.

Important Dates

January 15th: Deadline for submissions

March 15th: Feedback given to authors

March 31st: Revised versions due

May 15th: Authors notified of decisions, possible second-round reviews

July 1st: Final notifications sent to authors

August 1st: Authors submit final camera-ready manuscripts for copyediting and layout stages

December: Publication

Submission

The Journal of Human-Robot Interaction is a peer-reviewed, interdisciplinary, open-access journal using an online submission and manuscript tracking system. To submit your paper, please:

- (1) Go to <http://humanrobotinteraction.org/journal/index.php/HRI/login> and login or follow the link to register with the site. If registering, click the buttons at the bottom of author and reviewer.
- (2) Login, follow link to user home, and click the “new submission” link on the lower right.
- (3) Follow the instructions for submission.

Guest Editors

Ryan Calo
University of Washington School of Law
rcalo@uw.edu

Kate Darling
MIT Media Lab
kdarling@mit.edu